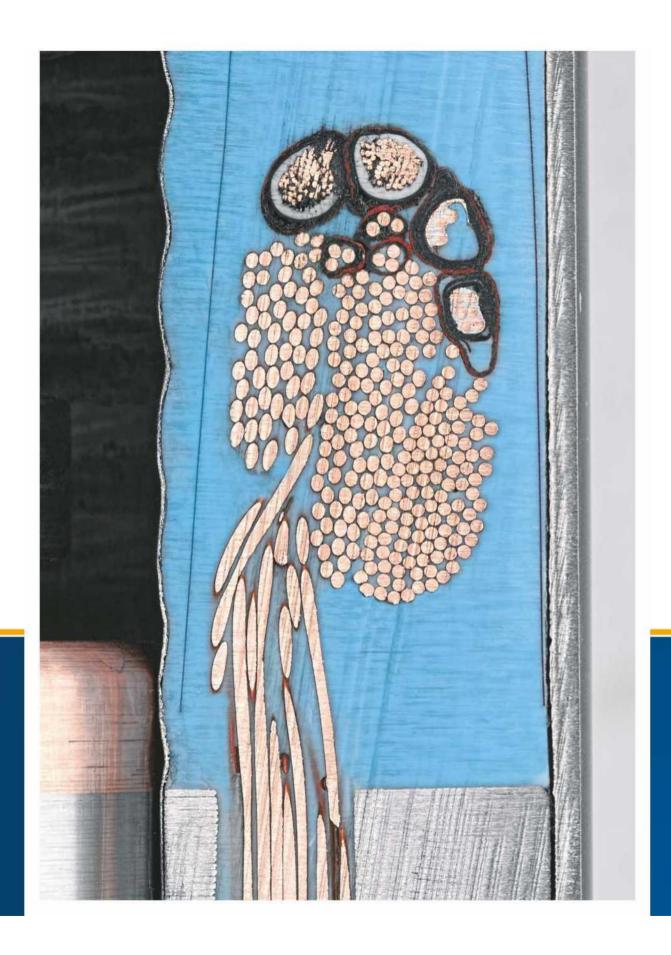


6" ENCAPSULATED SUBMERSIBLE MOTORS





Encapsulated Submersible Motor





6" ENCAPSULATED SUBMERSIBLE MOTORS 50/60 HZ



6" ENCAPSULATED SUBMERSIBLE MOTORS

Water cooled motors with encapsulated resin filled stator.

Coupling dimensions and flange according to NEMA standard.

2 - 3

General Features

- 5,5-60 HP / 3PH. 380-415 Volts / 50Hz
- ▶ High efficiency provides operation cost savings
- ▶ Motor casing and shaft made of AISI304L stainless steel (Optional AISI316L)
- ▶ High resistance coated cast iron upper and lower bracket (Optional AISI304L / AISI316L)
- ▶ Water lubricated Kingsbury type thrust bearings
- ▶ Protection IP68
- Sand slinger protection
- ▶ Pressure equalizing diaphragm
- ▶ Insulation class F
- Removable lead cable
- Starting method D.O.L. and star/delta



Operating Limits

- ► Max. voltage fluctuation: ±10%
- ▶ Max. water temperature: 35°C with at least 0.16 m/s of water flow speed
- Max. motor startings per hour: 20
- ► Max. immersion depth: 350 m
- Standard mounting position: vertical and horizontal

6" Encapsulated Submersible Motors



Slinger (sand guard)
Slinger helps to prevent the sand inside the water of the well entering in mechanical seal and through mechanical seal to inside of the motor.



High thrust capacity
Heavy duty bearings provides
the option to revolve both
sides, has the capacity to
carry high thrust load.



Adjustment screw Standard shaft height can be precisely adjusted by the adjustment screw on the thrust bearing base.



Up-Thrust ring
Provides safe operation
conditions for motor by
absorbing Up-Thrust loads
with it's machined surface
and water channels on it.



6" Encapsulated Submersible Motors



Practical cable connection

Extremely simple and very practical power cable connection to the motor body.



Water lubricated radial carbon bearings

Radial carbon bearings, which have channels in its structure that makes it possible to get lubricated by water easily, provides precise bearing of rotor shaft at up and down.



High quality mechanical sealing system

High sand resistance and degree of IP68 protection. Although mechanical seal is optionally used by other companies, it is always used by Çiftsan as a standard, to prevent sand and other particles to get in motors to provide long bearing life.



Pressure balancing checkvalve

When the pressure increases, it throw water out of the motor. When the pressure drops, it filtrates the water inside well and gets it inside the motor by the help of this checkvalve to balance the pressure inside. That's why pressure differences inside motor never causes membrane under motor to blow up.

VSM1.06/4.0-3PH.F50.V380-DCX

Mech. Seal (X:Ceramic Carbon, Y:SiC/SiC)
Casting (C:GG25, S:AISI304, N:AISI316)
Starting (D:DOL, S:Star/Delta)
Voltage Value Frequency (50Hz, 60Hz)
Phase Type Motor Power (kW)
Vansan Product Type

Part List

No	Part Name	Material
1	Stator	-
1.1	Winding wire	Copper
1.2 1.3	Stator package Stator shell	M700-50A / Magnetic Seal AISI 304
2 2.1	Rotor Shaft sleeve	- Coated CrNi
2.2 2.3	Balance ring Copper ring	St 37 Cu
3	Radial bearing	Carbon
4 5	Upper bearing body Bushing	GG20-22 Bronze
6	Slinger (sand guard)	NBR_EPDM
7	Hexagon socket cap screws	lnox
8	Copper ring	Cu
9	Cover seal	AISI 420
10	Mechanical seal	Ceramic Carbon
11	Axial thrust bearing key	AISI 420
12	Axial thrust bearing	Carbon With Antimony
13 14	Retaining ring Tie rod	St 37 Inox
16	Thrust bearing support	GG20-22
17	Ball holder	St 37 (Coated Cr+3)
18	Thrust bearing ball	lnox
19	Tilting pads	AISI 420
20	O-ring	NBR 70
21	Thrust bearing body	GG20
23	Nut	Inox
24	Screw (thrust bearing base)	Inox
25	Membrane	NBR-EPDM
26	Membrane body	GG22
27	Hexagon socket cap screws	Inox
28	Check-valve	Bronze
29	O-ring	NBR 70
30	Cable seal	NBR
31	Seal cover	AISI 304
32	Nut	Inox
33	Plush (r 3/8")	Bronze
34	Ball holder pins	Inox

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Encapsulated Submersible Motor Technical Drawing



6" Encapsulated Motor Data Table (Three-Phase) ${f 50~Hz}$

Туре		P _N	Axial Load	Voltage	n _N	I N	IA		ifficien	ісу (%		Cos(D load)	(%	TN	TA	Motor Length	ত্র Motor Weight
	HP	kW	kN	٧	rpm	Α	Α	50	75	100	50	75	100	Nm	Nm	≥ mm	<u>≥</u> Kg
VSM1.06/4.0-3ph.f50.V380- DCX	5,5	4	20	380	2850	9,2	34,0	78,5	80,3	79,0	0,75	0,82	0,83	13,4	18,0	578	42
VSM1.06/5.5-3ph.f50.V380- DCX	7,5	5,5	20	380	2770	12,4	48,0	78,5	80,3	78,3	0,80	0,83	0,86	18,8	28,7	598	44
VSM1.06/7.5-3ph.f50.V380- DCX	10	7,5	20	380	2840	16,5	69,0	77,7	80,5	80,2	0,76	0,83	0,86	25,0	44,2	653	50,5
VSM1.06/9.3-3ph.f50.V380- DCX	12,5	9,3	20	380	2840	20,3	94,6	79,6	81,8	80,5	0,76	0,83	0,87	31,2	56,0	681	53
VSM1.06/11.0-3ph.f50.V380- DCX	15	11	20	380	2840	23,6	90,0	80,3	82,6	81,0	0,77	0,82	0,87	37,0	70,0	718	57
VSM1.06/13.0-3ph.f50.V380- DCX	17,5	13	20	380	2860	27,6	145,2	79,8	82,3	81,5	0,80	0,84	0,87	43,5	85,0	753	60,5
VSM1.06/15 0-3ph.f50.V380- DCX	20	15	20	380	2845	32,1	181,0	80,1	82,6	81,5	0,79	0,85	0,87	50,3	98,0	798	65,5
VSM1.06/18 5-3ph.f50.V380- DCX	25	18,5	20	380	2860	40,5	246,0	79,4	82,3	82,0	0,77	0,82	0,85	61,6	137	858	72,5
VSM1.06/22.0-3ph.f50.V380- DCX	30	22	20	380	2850	47,5	279,0	81,2	83,2	82,2	0,78	0,84	0,86	73,6	157	898	75,5
VSM1.06/26.5-3ph.f50.V380- DCX	35	26,5	26	380	2850	57,9	338,0	81,7	83,7	82,5	0,76	0,81	0,84	88,7	193	983	88
VSM1.06/30.0-3ph.f50.V380- DCX	40	30	26,5	380	2870	64,5	412,0	80,2	82,9	83,0	0,77	0,83	0,85	99,2	239	1063	92
VSM1.06/37.0-3ph.f50.V380- DCX	50	37	26,5	380	2860	80,0	478,0	80,3	82,8	83,0	0,75	0,81	0,85	124	248	1198	95
VSM1.06/45.0-3ph.f50.V380- DCX	60	45	26,5	380	2850	96,5	520,0	81,6	83,7	83,0	0,77	0,83	0,85	151	286	1273	98

VSM 1.06 (3ph-50 Hz)

Motor Power Range	5,5 HP - 60 HP
Thrust Load Capacity	5,5 HP - 30 HP = 20,0 kN 35.0 HP - 60 HP = 26.5 kN
Outside Diameter	142 mm
Flange Standard	6" NEMA Standard



6" Encapsulated Motor Data Table (Three-Phase) 60 Hz

Туре		P _N	Axial Load	Voltage	n _N	N	I A	le	oad)	ncy (%	50	Cos(D load)		TN	TA	Motor Length	조Motor Weight
	HP	kW	kN	٧	rpm		Α	50	75	100	50	75	100	Nm	Nm	mm	Kg
VSM1.06/4.0-3ph.f60.V460-	5,5	4	20	460 380 220			32,0 38,7 66,9	71.1 71.1 70.0	75.9 75.9 75.0	77.7 77.7 77.0	0.73 0.73 0.73	0.79 0.79 0.79	0.83 0.83 0.83	10,9 11,0 11,2	18,1 18,4 19,0	578	42
VSM1.06/5.5-3ph.f60.V460-	7,5	5,5	20	460 380 220	3430 3425 3415	9,8 11,9 20,5	52,5 63,6 109,8		78.6 78.6 77.5	80.0 80.0 79.0	0.79 0.79 0.79	0.83 0.83 0.83	0.88 0.88 0.88	15,5	29,2 29,5 30,1	598	44
VSM1.06/7.5-3ph.f60.V460-	10	7,5	20	460 380 220		14,2 17,2 29,7	156,8		75.6 75.6 74.7	78.1 78.1 77.1	0.74 0.74 0.79	0.81 0.81 0.83	0.85 0.85 0.88	20,6 20,8	44,8 45,1 45,7	653	50,5
VSM1.06/9.3-3ph.f60.V460-	12,5	9,3	20	460 380 220		16,9 20,5 35,3	103,0 124,7 215,4	72.0	77.5 77.5 77.0	79.5 79.5 78.5	0.75 0.75 0.79	0.82 0.82 0.83	0.87 0.87 0.88	25,5 25,6 25,8	57,0 57,3 57,9	681	53
VSM1.06/11.0-3ph.f60.V460-	15	11	20	460 380 220		18,0 21,8 37,6	97,2 117,7 203,2		78.1 78.1 77.2	85.5 85.5 84.5	0.75 0.75 0.75	0.81 0.81 0.81	0.90 0.90 0.90	30,1 30,2 30,4	71,0 71,3 71,9	718	57
VSM1.06/13.0-3ph.f60.V460-	17,5	13	20	460 380 220	3490	23,2 28,1 48,5	157,0 190,1 328,3	72.1	77.7 77.7 77.0	79.9 79.9 79.0	0.77 0.77 0.77	0.82 0.82 0.82	0.87 0.87 0.87	35,6 35,7 35,9	85,0 85,3 85,9	753	60,5
VSM1.06/15.0-3ph.f60.V460-	20	15	20	460 380 220	3480	26,4 32,0 55,2	195,0 236,1 407,7	72.3	77.9 77.9 77.0	80.1 80.1 79.2	0.77 0.77 0.77	0.81 0.81 0.81	0.86 0.86 0.86	41,1 41,2 41,4	98,0 98,3 98,9	798	65,5
VSM1.06/18.5-3ph.f60.V460-	25	18,5	20	460 380 220	3490 3485	34,1 41,3 71,3	265,0 320,8 554,1	71.8 71.8	77.5 77.5 76.5		0.74 0.74 0.74	0.80 0.80 0.80	0.85 0.85 0.85	50,5	138,0 138,3 138,9	858	72,5
VSM1.06/22.0-3ph.f60.V460-	30	22	20	460 380 220	3485 3480	39,5 47,8 82,6	300,0 363,2 627,3	74.4 74.4	79.3 79.3 79.3	81.1 81.1 80.1	0.75 0.75 0.75	0.80 0.80 0.80	0.86 0.86 0.86	60,2	157,0 157,3 157,9	898	75,5
VSM1.06/26.5-3ph.f60.V460-	35	26,5	26	460 380 220	3480 3475	47,1 57,0 98,5	363,0 439,4 759,0	74.8 74.8	79.7 79.7 78.8	81.5 81.5	0.74 0.74 0.74	0.80 0.80 0.80	0.87 0.87 0.87	72,5 72,6	193,0 193,3 193,9	983	88
VSM1.06/30.0-3ph.f60.V460-	40	30	26,5	460 380 220	3490	55,6 67,3	444,0 537,5 928,4	73.1 73.1	78.4 78.4 77.5	80.7 80.7	0.74 0.74 0.74	0.80 0.80 0.80	0.84 0.84 0.84	81,6 81,7	240,0 240,3 240,9	1063	92
VSM1.06/37.0-3ph.f60.V460-	50	37	26,5	460 380 220	3480 3475	69,0 83,5 144,3	516,0 624,6	73.4 73.4	78.6 78.6	80.8 80.8	0.70 0.70 0.70	0.78 0.78 0.78	0.83 0.83 0.83	100,7 100,8	249,0 249,3 249,9	1198	95
VSM1.06/45.0-3ph.f60.V460-	60	45	26,5	460 380 220	3480 3475	81,0 98,1 169,4	559,0 676,7	75.4 75.4	80.1 80.1	81.9	0.73 0.73 0.73	0.80 0.80 0.80	0.85 0.85 0.85	123,5 123,6	286,0 286,3 286,9	1273	98

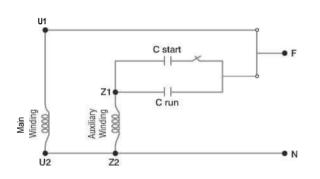
10 - 11

VSM 1.06 (3ph-60 Hz)

Motor Power Range	5,5 HP - 60 HP
Thrust Load Capacity	5,5 HP - 30 HP = 20,0 kN 35.0 HP - 60 HP = 26.5 kN
Outside Diameter	142 mm
Flange Standard	6" NEMA Standard

Туре		P _N	Axial Load	Voltage	Full	Load	SF ·	1.15	n _N		Effic y load)	(%	Cos(load)	•	le Size	Cable Length	Motor Length	Motor Weight
	HP	kW	kN	٧	Amps	Watt	Amps	Watt	rpm	Α	sf	fl	sf	fl	mm²	m	mm	Kg
VSM1.6/5.5-1PH.F60.V230- DCX	7,5	5,5	20	230	Y36.8 B34.6 R5.5		8600	8780	3445	171	73	73	0,89	0,89	3x6	4	598	43
VSM1.6/7.5-1PH.F60.V230- DCX	10	7,5	20	230	Y45.2 B40.6 R9.5		11200	11500	3450	209	75	76	0,94	0,95	3x6	4	653	48
VSM1.6/11 -1 PH.F60.V230- DCX	12,5	11	20	230	Y62.4 B51.8 R17.5	13900	15900	16200	3460	305	78	79	0,96	0,97	3x1 0	4	718	55

LEAD CABLE CONNECTION INSTRUCTIONS (For 6" Single Phase (60Hz / 7,5 HP / 10 HP / 15HP motors)

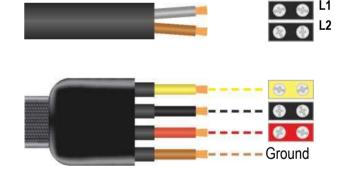


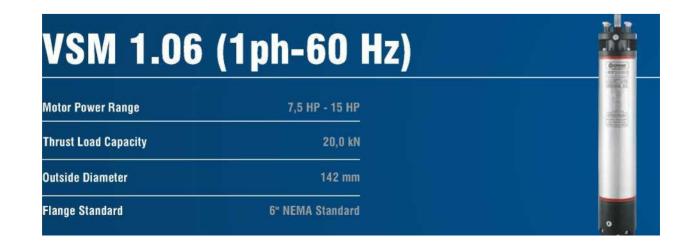


- a) Yellow (Neutral)
- b) Black (Main)
- c) Red (Auxiliary)
- d) Braun (Ground)

Capasitor [uF]								
Power	C Start	C Run						
7,5 Hp	145	130						
10 Hp	280	140						
15 Hp	300	200						

"US" CONTROL PANEL CONNECTION SCHEMA



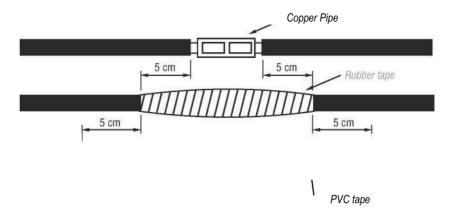


CABLE SELECTION TABLE (DOL) CABLE SELECTION TABLE (Wye - Delta)

НР						Cable Sizes	3				
	3x1,5	3x2,5	3x4	3x6	3x10	3x16	3x25	3x35	3x50	3x70	3x95
5,5	97	161	258	388	646	1.033	1.615	2.261	3.230	4.521	6.136
7,5	72	121	193	290	483	773	1.207	1.690	2.415	3.381	4.588
10	57	96	153	230	383	613	958	1.342	1.916	2.683	3.641
12,5	47	78	125	188	313	501	783	1.096	1.565	2.191	2.974
15	41	68	109	163	271	434	678	949	1.356	1.899	2.577
17,5	34	57	92	138	230	367	574	803	1.148	1.607	2.181
20	29	49	79	118	196	314	491	688	982	1.375	1.867
25		40	64	96	159	255	398	558	797	1.115	1.514
30			54	81	136	217	339	475	678	949	1.288
35			46	68	114	182	285	399	570	798	1.083
40				60	101	161	252	352	503	705	956
50					84	134	209	293	418	585	794
60					69	110	172	241	344	481	653
70					59	95	149	208	297	416	565
75						90	141	197	281	394	534
80						82	129	180	258	361	490
90						74	115	162	231	323	439
100							103	144	206	289	392
110							95	134	191	267	363
125								118	168	235	319
150								101	144	201	273
175									123	172	233
200										152	207
210										145	196
225										136	184
250											164

10 - 11

Other Features



Power Cable Connection

Connection of the power cable that will be used along the well and until the control panel with the power cable on the motor must be done very carefully and by the professionals only. Unless the insulation after the connection is well done, short circuit might happen when the connection area is in the water.

Insulation of each cable should be stripped only as far as necessary to provide room for a stake type connector. Each individual joint should be taped with pvc tape, using two layers by wrapping tightly for eliminating airspaces as much as possible.

Total thickness of tape should be no less than the thickness of the cable insulation in order to prevent the smashing of the cables when the pump is lowered in the well.

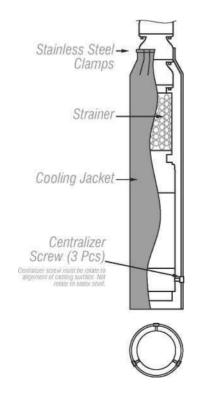


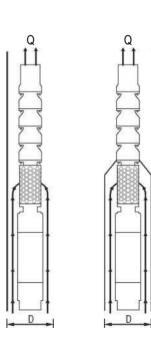
Use Cooling Jacket

Cooling of submersible motors is provided with the flow of the water around it. That's why water flow around motors has vital importance during submersible pump installation. This flow rate depends on diameter and power of motor.

Most important factor of submersible motors' long service life is that the motor has to be cooled well. Required flow velocity around the motor is given in the table below for motors being cooled well enough.

If the motor will be installed in an open body of water (i. e pool) or diameter of the well is much bigger than the diameter of the motor, Flow Inducer Sleeve must be used to provide the flow velocities that are given in the table below, around the motor.





Insulation Resistance Test

All Çiftsan motors are applied insulation test under 3.000 V before shipment. Motors which have at least 2.000 megaohm test result are shipped. Insulation test results should be controlled before the installation and after connecting power cables as it is explanied below. Meger tester's one probe should be touched to motor body and other probe should be touched to tip of each power cable to measure the insulation of each phase. If there is any short circuit in a phase, insulation value is 0 megaohm.

Under the normal operating conditions, a motor inside the well should have 2 megaohm insulation resistance. When the insulation resistance drops under 0.5 megaohm, there might be a insulation problem in winding. Test voltage should be at least 500 V DC.

After extending power cables with a joint, same test procedures should be also applied for insulation control while power cables are inside water. If insulation test result for any winding is lower than 100 megaohm, cable joint should be done again.





Use Frequency Convertor and Soft Starter

These points listed below should be taken into consideration while operating submersible motors with frequency convertor and soft starter.

- Needed precautions should have been taken to protect your frequency convertor from voltage flactuations.
- Flow rate around motor must be at least 0.15 m/s. If flow rate is not enough, flow inducer sleeve must be used to provide the needed flow rate.
- In systems which are operated by frequency convertor and soft starter, motor selection should be done as choosing next higher motor rate for pumps will provide long service life for motors.
- Motors should be operated between 30-50 Hz with frequency convertors. As the protective water layer can't be formed on thrust bearing at the lower frequencies, motor would get damaged.
- Dual slope frequency convertors should be used while using soft starter too.



Voltage Drop and Cable Power Loss

To determine the cable section it should be considered that the voltage drop must not exceed 3%. The formulas used for voltage drop calculation are given below.

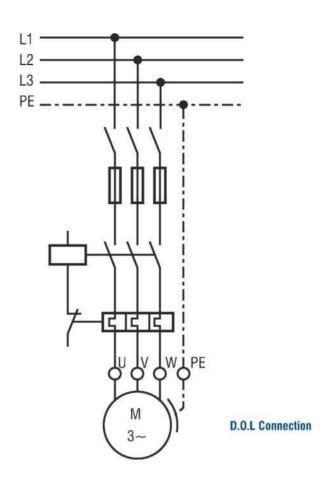
Direct starter (1 cable)	3,1xLxlxcoscp qxl)	3,1xLxlxcos <p< th=""><th>L : Cable length (m)</th></p<>	L : Cable length (m)
Direct starter (2 cables in parallel)	1,55xLxlxcoscp u _v = qxll	1,55xl_xlxcos <p< td=""><td>I : Current at nominal voltage (A) q : Condutor section (mm2) cos? : Power factor Pv : Power loss (%)</td></p<>	I : Current at nominal voltage (A) q : Condutor section (mm2) cos? : Power factor Pv : Power loss (%)
Star-delta starter	11 2,1xLxlxcos(p ^v- qxÜ	q = ^{2,1xl_xlxcos(p} U,,%xU	UV : Voltage drop (%) U : Nominal voltage (V)

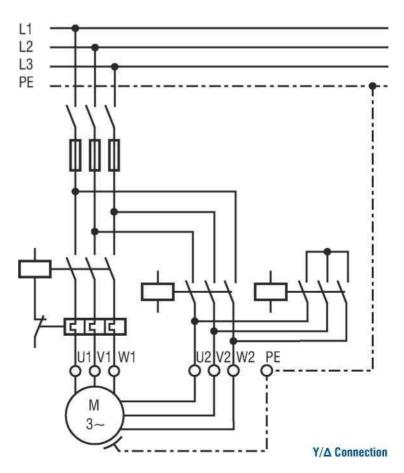
The power loss along the feeling cable has to be calculated adjacent to:



Energy Connection Schema







Trouble Shooting

Motor Does Not Start

Possible Cause	Remedy
No power or incorrect voltage	Check voltage at lines. Contact power company if voltage is incorrect
Fuses blown or circuit breakers tripped	Replace with proper fuse or resetcircuit breakers
Control box malfunction	Repair or replace
Defective wiring	Correct faulty wiring or connections
Bound pump	Pull pump and correct problem. Run new installation until the water cleans
Defective cable or motor	Repair or replace

Motor Starts Too Often

Possible Cause	Remedy
Check valve stuck open	Replace if defective
Waterlogged tank	Repair or replace
Lenk in system	Replace damaged pipes or repair leaks

Motor Runs Continuously

Possible Cause	Remedy
Low water level in well	Throttle pump outlet or reset pump to lower level. Do not lower if sand may clog pump
Worn pump	Pull pump and replace worn parts
Loose coupling or broken motor shaft	Replace worn or damaged parts
Pump screen blocked	Clean screen and rest pump depth
Check valve stuck closed	Replace if defective
Control box malfunction	Repair or replace

Motor Runs But Overload Protector Trips

Possible Cause	Remedy
Incorrect voltage	Contact power company if voltage is incorrect
Overheated protectors	Shade box, provide ventilation or move box away from source
Defective control box	Repair or replace
Defective motor or cable	Repair or replace
Worn pump or motor	Replace pump and/or motor

